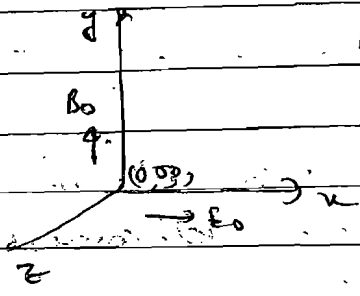


magnetism solution

Theory

Set 4

1

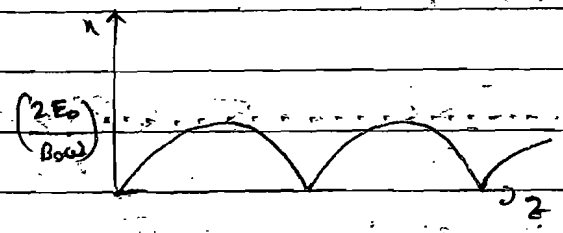


(A) is correct

Particle is released from rest.

$$v_x = \frac{E_0 \sin \omega t}{B_0} \quad (\omega = \frac{qB_0}{m})$$

$$v_z = \frac{E_0 (1 - \cos \omega t)}{B_0}$$



$\vec{v} \neq \text{const}$ so (B) wrong

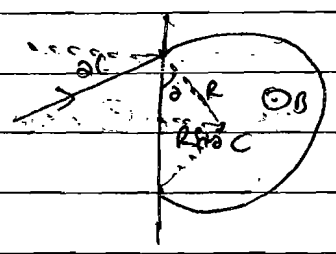
$$a_x = \frac{q}{m} (E_0 - v_z B_0)$$

$$a_z = \frac{q}{m} v_x B_0$$

$v_x = v_z = 0$ at $\omega t = 0, \pi, 2\pi$ etc. so (C) is correct

(D) is correct

2

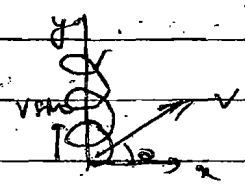


(A) is correct

Right \rightarrow R if $0 \rightarrow \pi$ so particle can't do

a complete circular path (A)

3



(A) is correct

4

$$P = \vec{F} \cdot \vec{v} \quad \& \quad \vec{F} = q \vec{v} \times \vec{B} \quad \text{so } \vec{F} \perp \vec{v}$$

so $P = 0$ (A) is correct.

5

If $q/vB \geq \pi E$ i.e. $E \geq vB$ so path will be like

Other will be non-circular path.

so (A) & (C) will correct.

(6) $\frac{1}{2}mv^2 = KE = qV$ So as q is same for both the isotopes (1)

isotopes So, KE will be equal for both the isotopes So A is

Correct

As $F \perp v$ So, KE const B is correct

they trace circular arc So C is correct D is correct

like left of $O(2)$

(7) $R = \frac{mv}{qB} = \frac{\sqrt{2mk}}{qB}$ $R \propto \sqrt{m}$ So C is correct (2)
 A is wrong

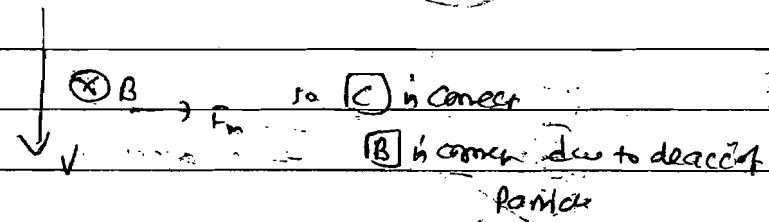
$W = \frac{v}{R} = \frac{qB}{m}$ $\therefore W \propto \frac{1}{m}$ So B is wrong

$\frac{R_1}{R_2} = \frac{P_1}{P_2}$ So D is correct

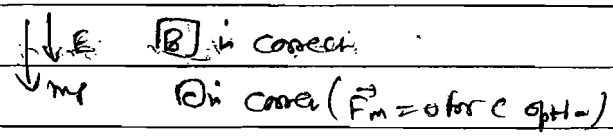
(8) If $v \perp B \Rightarrow qvB = E = vB$, $v = \text{const}$ A is correct (3)

If $E = 0$ then $w = 0$ So $KE = \text{const}$ C is correct

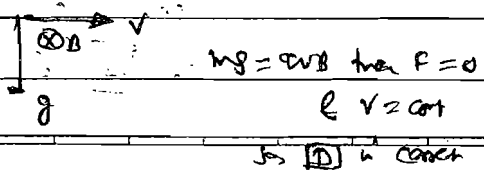
(9)



(10) IF E horizontally It will deflect (4)

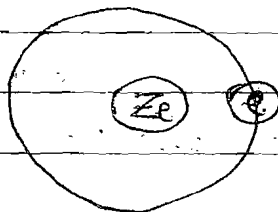


Consider a case when particle is projected horizontally



Set 2

①



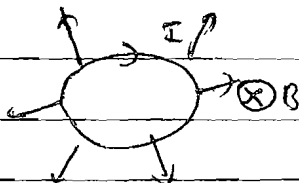
A) h correct according to active part.

B) h correct as h is mostly.

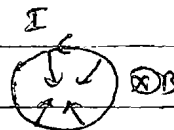
C) h correct as I exists.

D) h correct $\propto \frac{1}{r}$

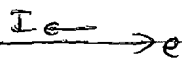
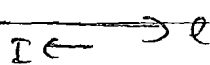
②



$F_{net} = 0$ [A] [B] [C] are correct



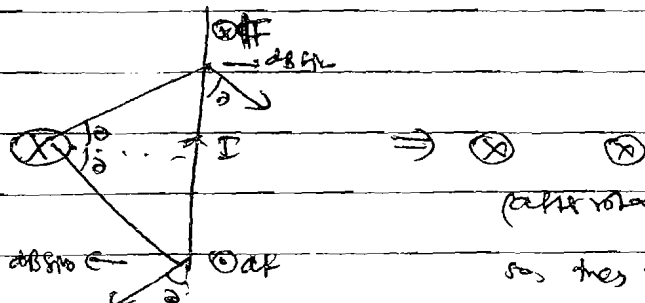
③



excitator
 due to repulsion initially beam
 tends to spread but due to mag
 an² narrow down later.

[B] [D] are correct.

④

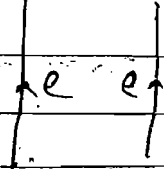


(after rotation)

so this approach (correct)
 each other

so [C] is alone correct

(A)



Initially - $\frac{2\pi\epsilon_0 R}{\ln 2}$
 then $\frac{2\pi\epsilon_0 R}{\ln 2}$

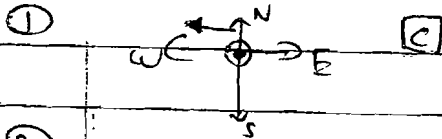
A B are correct

(B)

B is correct for circle area in maximum

$M = IA$ Max

Sets:



②
$$B_p = \frac{\mu_0 I}{4\pi r} (\sin(90-\alpha_2) + \sin(90-\alpha_1)) = \frac{\mu_0 I}{4\pi r} (\cos\alpha_1 + \cos\alpha_2)$$
 [A]

③ [D]

④ [A] For any symmetrical loop $B_{\text{center}} = 0$ if current enter at a point & leave from other point

⑤
$$B_o = \frac{\mu_0 I}{4\pi r} \odot + \frac{\mu_0 I}{4\pi r} \odot = \frac{\mu_0 I}{2\pi r} \odot$$
 [C]

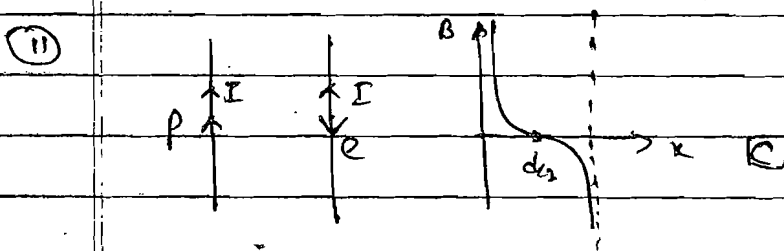
⑥ [C]

⑦
$$B = \frac{\mu_0 I}{4\pi r_1} + \frac{\mu_0 I}{4\pi r_2} = \frac{\mu_0 I}{2r_1} + \frac{\mu_0 I}{2r_2} = \frac{\mu_0 I}{r}$$
 [D]

⑧ [C] Hold current carrying wire above you then will get direction of B.

⑨
$$\left(\frac{\mu_0 I}{4\pi r} \right) \left(\frac{1}{r_1} \right) = \frac{\mu_0 I}{8r}$$
 [C]

⑩
$$\left(\frac{\mu_0 I}{4r_1} - \frac{\mu_0 I}{4r_2} \right) = \frac{\mu_0 I}{4} \left(\frac{1}{r_1} - \frac{1}{r_2} \right)$$
 [D]

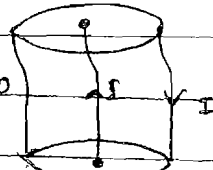


Set 4

① $B_{out} = \mu_0 \epsilon_{in} \quad \mathcal{E}_{in} = 0$
 $\therefore B = 0 \quad \text{for } 6 \leq r < r_1$

□

② $B_{out} = 0 \Rightarrow B_2 = 0$
 $B_{in} \neq 0 \Rightarrow B_1 \neq 0$



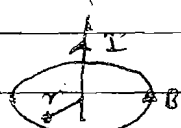
□

③ $B_{in} \neq 0 \Rightarrow B_1 \neq 0$
 $B_{out} \neq 0 \Rightarrow B_2 \neq 0$ **A**

④ $B_1 = \frac{\mu_0 I}{2\pi r_1} \quad B_2 = \frac{\mu_0 I}{2\pi r_2} = \frac{\mu_0 I}{2\pi r_1}$

$\Rightarrow B_1 = B_2$ **A**

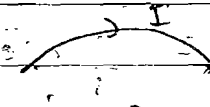
⑤



$I \neq 0 \text{ if } R \neq \infty$
 \Rightarrow **D**

Exercise 1

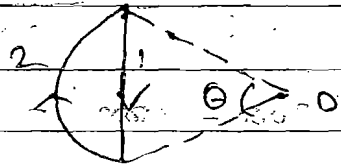
Single option is correct:

① Use $B = \frac{\mu_0 I \theta}{4\pi r}$ 

$$B_{\text{center}} = \frac{\mu_0 I (\pi)}{4\pi R} (\otimes) + \frac{\mu_0 I (3\pi)}{4\pi R'} (\otimes)$$

$$\therefore B_{\text{center}} = \frac{\mu_0 I}{8} \left(\frac{1}{R} + \frac{3}{R'} \right) (\otimes) \quad \boxed{\text{(D)}}$$

②



$$B_1 = \frac{\mu_0 I}{4\pi R \cos \theta} \left[\frac{8\mu_0}{2} + \frac{8\mu_0}{2} \right] (\otimes)$$

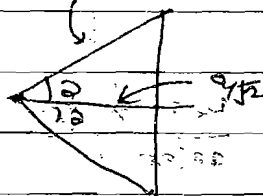
$$B_1 = \frac{\mu_0 I \tan \theta}{2R} (\otimes)$$

$$B_2 = \frac{\mu_0 I \theta}{2\pi R} (\otimes)$$

$$B_{\text{net}} = \vec{B}_1 + \vec{B}_2 = \frac{\mu_0 I}{\pi R} \left(\frac{\tan \theta}{2} - \frac{\theta}{2} \right) (\otimes) \quad \boxed{\text{(C)}}$$

$\theta = \frac{\pi}{3}$ $(\tan \theta)_\theta$

③



$$B = \frac{\mu_0 I (2\sin \theta)}{4\pi R \sin \theta} = \frac{\mu_0 I}{2\pi R \sin \theta}$$

$$\cos \theta = \frac{R}{\sqrt{2}} = \frac{1}{\sqrt{2}} \quad B = \frac{\mu_0 I}{(2\pi R) \left(\frac{1}{\sqrt{2}} \right)}$$



$$B_{\text{net}} = 4B \cos \theta = \frac{\mu_0 I}{\sqrt{2}\pi R} \cdot 4 \cdot \frac{1}{\sqrt{2}} = \frac{2\mu_0 I}{\pi R} (\otimes)$$

$\boxed{\text{(C)}}$

(4) $B = \frac{\mu_0 I \sqrt{2} \times r}{4r^2}$
 $= \frac{10^{-7} \times 2 \times 100 \times \sqrt{2}}{4 \times 30^2}$

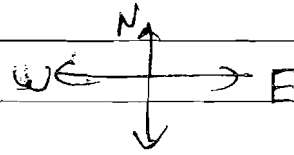
$= \frac{1}{4} \times 10^{-5} = 2.5 \times 10^{-6} \text{ T} \quad \text{(A)}$

(5)

$\vec{B} = \frac{\mu_0 I}{2R} (\hat{i} + \hat{j} + \hat{k}) \Rightarrow |\vec{B}| = \frac{\sqrt{3} \mu_0 I}{2R} \quad \text{(A)}$

(6)

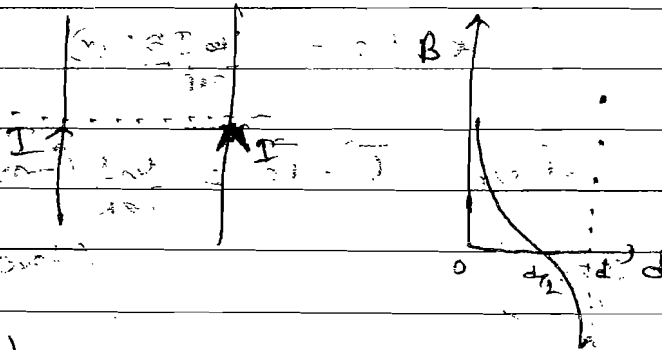
$B_{\text{net}} = \frac{\mu_0 I N_1}{2R_1} - \frac{\mu_0 I N_2}{2R_2}$



$= \frac{4\pi \times 10^{-7}}{2} \left[\frac{16 \times 20}{0.16} - \frac{25 \times 18}{0.10} \right]$

$= 2\pi \times 10^{-7} (2000 - 4500) = 5000\pi \times 10^{-7} \text{ T}$
 $= 5\pi \times 10^{-4} \text{ T} \quad \text{(A)}$

(7)



(D)

(8) (A)

(9) $B_{\text{net}} = \left(\frac{\mu_0 I}{4\pi r} + \frac{\mu_0 I}{4\pi r} \right)$

$= \frac{\mu_0 I}{4\pi} \left(\frac{1+1}{2} \right) = \left(\frac{3\mu_0 I}{8\pi} \right) \quad \text{(A)}$

(10)

$B_{\text{net}} = \frac{\mu_0 I}{4\pi \times 0.30} - \frac{\mu_0 I}{8\pi \times 0.30} + \frac{\mu_0 I}{12\pi \times 0.30}$

$= \frac{\mu_0 I}{4\pi \times 0.30} (1 - 1 + 1)$

(11)

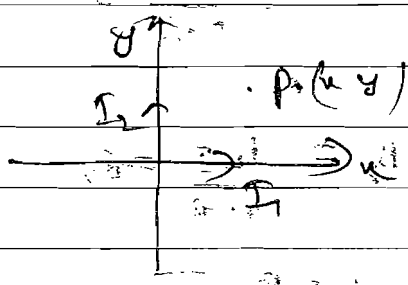
$$B_2 = \frac{\mu_0 I \times 2}{2r} = \frac{2\mu_0 I}{R}, B_1 = \frac{\mu_0 I}{2R}$$

$$\frac{4\mu_0 I}{2R} = \frac{2\mu_0 I}{R} \therefore r = \frac{R}{2}$$

$$\frac{B_2}{B_1} = \frac{4}{1} \quad \boxed{B}$$

A

(12)



$$B_p = 0$$

$$\therefore \frac{\mu_0 I_2}{2\pi r} = \frac{\mu_0 I_1}{2\pi y}$$

$$y = x \left(\frac{I_1}{I_2} \right) \quad \boxed{C}$$

(13)

$$B_{net} = \frac{\mu_0 I}{4\pi d \cos 45^\circ} (\sin 90^\circ - \sin 45^\circ) \times 2$$

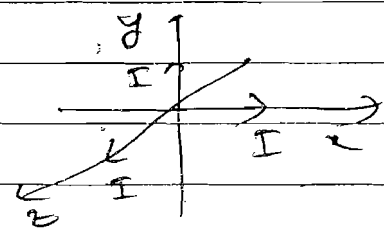
$$= \left(\frac{\mu_0 I}{4\pi d \sqrt{2}} \right) (1 - \frac{1}{\sqrt{2}}) \times 2$$

$$B_{net} = \frac{\mu_0 I}{\sqrt{2} \pi d} \left(1 - \frac{1}{\sqrt{2}} \right) \quad \boxed{A}$$

(14)

$$B_{net} = \frac{\mu_0 I}{2\pi a} \uparrow$$

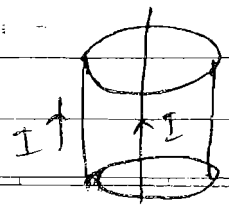
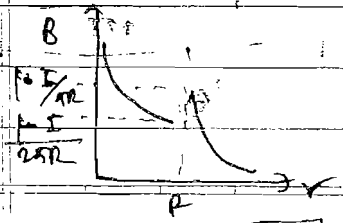
$$\frac{\mu_0 I}{2\pi a} \uparrow$$



$$B_{net} = \frac{\mu_0 I}{2\pi a} (\uparrow - \uparrow) \quad \boxed{A}$$

29m30

(15)

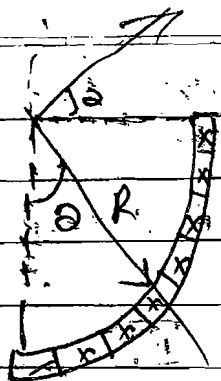


$$0 < r < R$$

$$B = \frac{\mu_0 I}{2\pi r}$$

$$\therefore B = \frac{\mu_0 I}{2\pi r}$$

(16)



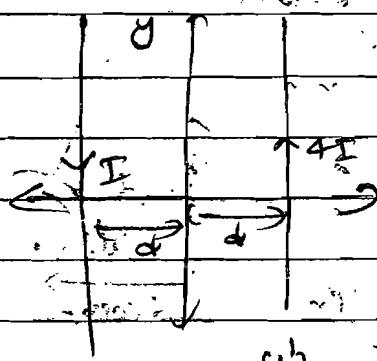
$$B = \int \frac{\mu_0 I d\ell \sin\theta}{4\pi R^2}$$

$$= \int_0^\pi \frac{\mu_0 I d\theta}{2\pi R} \cos\theta$$

$$B_H = \frac{\mu_0 I}{4\pi R} = B_V$$

$$B_{net} = \sqrt{2} B_H = \frac{\mu_0 I R}{4\pi R^2} [A]$$

(17)

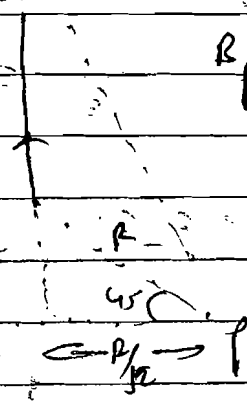


(b) direction of B is towards left

(c) B will tend to zero close to left

So, [C]

(18)



$$B_p = \frac{\mu_0 I}{4\pi R/\sqrt{2}} (\sin 90^\circ - \sin 45^\circ)$$

$$= \frac{\mu_0 I}{4\pi R/\sqrt{2}} (1 - \frac{1}{\sqrt{2}})$$

$$B_p = \frac{\mu_0 I (\sqrt{2} - 1)}{4\pi R} [A]$$

[A]

(19) Ampere's Law



$B_{AB} = 0$, $B_{CD} \propto B_0$ it will be same
 $\therefore B_0 = \mu_0 I$ $\therefore B = \mu_0 I$ [B]

(20) Use principle of superposition

$B_{total} = B_{(+)} + B_{(-)}$ (1)

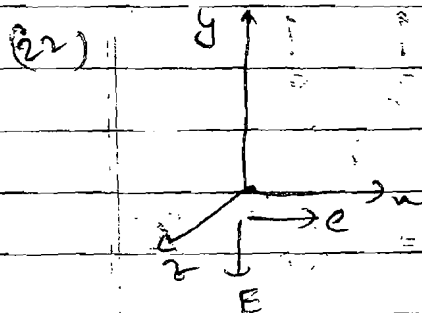
$B_{(-)} = 0$, $B_{(+)} = \frac{\mu_0 I}{2\pi r} = \frac{\mu_0 (I \cos \theta)}{2\pi r (b^2 - a^2)} = \frac{\mu_0 I}{2\pi (b^2 - a^2)}$

[B]

(21) $B = B_{left} + B_{right} = \left(\frac{\mu_0 I_{left}}{2\pi d_1} + \frac{\mu_0 I_{right}}{2\pi d_2} \right) \hat{j}$

$= \left(\frac{\mu_0 J \pi d_1^2}{2\pi d_1} + \frac{\mu_0 J \pi d_2^2}{2\pi d_2} \right) \hat{j}$

$= \frac{\mu_0 (J \pi d)}{2\pi} \hat{j}$ [A]



$F_E = \uparrow$

$F_B = \downarrow$

B show [B]

(23)

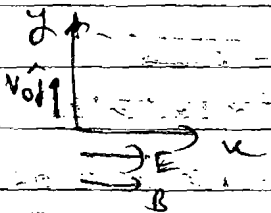
By work energy theorem $\Delta K = W$

$\Rightarrow \frac{1}{2} (mv)^2 = \frac{1}{2} mv^2 - E_0 d$

$\Rightarrow \frac{3}{2} mv^2 = E_0 d$

(23)

change in velocity = $\vec{v}_f - \vec{v}_i$
 $= (\vec{v}_{yB} + \vec{v}_x - v_0 \hat{j})$



$v_{yB}^2 + v_x^2 = 4v_0^2$
 $v_{yB} = v_0$
 $\therefore v_x = 3v_0 \therefore v_x = 3v_0$

So $\frac{qE}{m} t = 3v_0 \therefore t = \frac{3mv_0}{qE}$ (D)

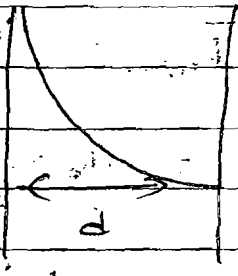
(24)

$qE = \frac{mv^2}{r_1}$ $q\sqrt{B} = \frac{mv}{r_2}$

$r_1 = \frac{mv^2}{qE}$ $r_2 = \frac{mv}{q\sqrt{B}}$

$\frac{r_1}{r_2} = \frac{\frac{mv^2}{qE} \cdot q\sqrt{B}}{mv} = \frac{v\sqrt{B}}{E}$ (D)

(25)



$d = r = \frac{mv}{qB}$

$v = \frac{dqB}{m}$ (B)

(26)

$F_E = \frac{q^2}{4\pi\epsilon_0 r^2}$ (1)

$F_B = \frac{\mu_0 q^2 v^2}{4\pi r^2}$ (2)

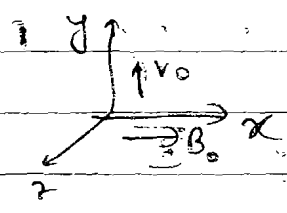
$\frac{F_E}{F_B} = \frac{\frac{q^2}{4\pi\epsilon_0 r^2}}{\frac{\mu_0 q^2 v^2}{4\pi r^2}} = \left(\frac{c^2}{v^2}\right)$ (A)

(27)

$t = \frac{1}{B_0 \omega} = \frac{2\pi}{B_0 \omega} = T \quad T = \frac{2\pi m}{qB}$

St line motion displacement = $v_0 \frac{T}{2}$
 $= \frac{v_0 \pi}{\omega}$

(35)



$$y=0, z = -2t = -2\left(\frac{mv}{qB}\right) = -\frac{2v}{B\alpha}$$

So, coordinates = $\left(\frac{v_0 t}{B\alpha}, 0, -\frac{2v_0}{B\alpha}\right)$ [D]

(28) $R = \frac{mv}{qB}$ H^+ $q=1, m=1$
 $R = \frac{\sqrt{2mk}}{qB}$ He^+ $q=1, m=4$
 $R \propto \sqrt{m}/q$ O^{+2} $q=2, m=16$

$R \propto \sqrt{m}/q$ $R_{H^+} \propto 1, R_{He^+} \propto 2, R_{O^{+2}} \propto 2$ [B]

(29) $R = \frac{\sqrt{2mk}}{qB}$ $R \propto \sqrt{k} \Rightarrow \frac{R_1}{R_2} = \left(\frac{k_1}{k_2}\right)^{1/2} \left(\frac{B_2}{B_1}\right)$

$\Rightarrow \frac{R}{R_2} = \frac{1}{\sqrt{2}} \Rightarrow R_2 = R\sqrt{2}$ [C]

(30) $qE = qvB \Rightarrow E = vB \Rightarrow v = \frac{E}{B}$
 $R = \left(\frac{mv}{qB}\right) = \left(\frac{mE}{qB^2}\right)$

$= \frac{9 \times 10^3 \times 3 \times 10^5}{16 \times 10^9 \times 4 \times 10^{-6}} = 4.5 \times 10^1 = 0.45 \text{ m}$ [C]

(31) AB V_{intra} along B & \perp to B so Helical [C]

(32) $B \uparrow (-v)$ also $qvB = F$
 $5 \times 10^3 = 1.6 \times 10^{19} \times 2.5 \times 10^3 \times B$
 $B = \frac{8}{2.5 \times 10^6} = \frac{2}{1.6} = \frac{5}{4} \text{ T}$
 Also $B \uparrow (-v)$ so [A]

(33) $2R = d = \frac{2mv}{qB}$ $qV_0 = \frac{1}{2}mv^2 \Rightarrow v = \sqrt{\frac{2qV_0}{m}}$

(34)

~~$\rho_{AB} = \frac{2\pi r^2}{R} \therefore \rho = \frac{2\pi r^2}{R} \cdot \frac{V}{AB} = \rho \times V$~~ B

①

(35)

~~$T = 2\pi R \cdot \left(\frac{2\pi r^2}{AB}\right)$~~ A

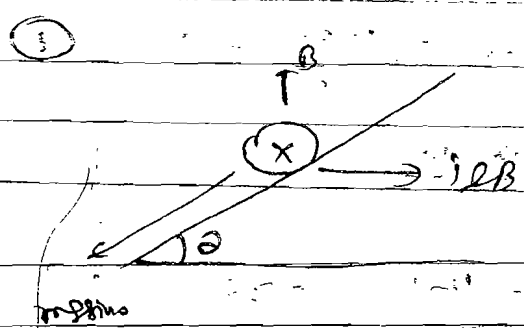
②

③

④

⑤

Exercise 2 (Mae)



$l \omega \cos \theta = \omega r \sin \theta$
 $\tan \theta = \left(\frac{l \omega \cos \theta}{mg} \right)$ [D]

(2)

$B = \left(\frac{\mu_0 I}{4\pi r \cos 30} (\sin 30 + \sin 30) \right) \times 2$
 $= \frac{\mu_0 I}{2\pi r} = \frac{\mu_0 I}{2\pi r}$ [A]

($r = l$) At equilibrium.

(3)

$F = \frac{3l}{2} \int \frac{\mu_0 I_1 I_2}{2\pi r} dr = \frac{\mu_0 I_1 I_2}{2\pi} \ln 3$ [B]

(4)

$B = \frac{\mu_0 I}{4\pi r \cos 45} (\sin 45 + \sin 45) + \frac{\mu_0 I}{4\pi r} \left(\frac{3\pi}{2} \right)$
 $= \frac{\mu_0 I}{2\pi r} + \frac{3\mu_0 I \pi}{8\pi r} = \frac{\mu_0 I}{8\pi r} (3\pi + 4)$ [D]

(5)

(A) $F_m = 0$

(6)

- (A) When q is projected along E , $v \neq \text{const}$
- (B) When q is projected along B , $v = \text{const}$
- (C) $E = 0, B = 0, v = \text{const}$
- (D) $E \neq 0, B \neq 0$, when $q \perp E = v \times B$ i.e. when $E = vB$

(7)

Ampere's law [B] [C] [D]

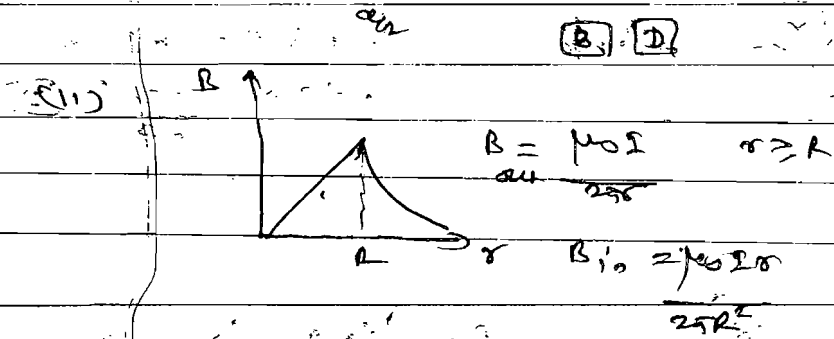
(8)

Radius $a = \frac{2m v}{qB} \Rightarrow k = \frac{P^2}{2m} \Rightarrow P = \sqrt{2mk}$
 $a = \frac{\sqrt{2mk}}{qB}, B = \frac{\sqrt{2mk}}{2a}$ [D]

(9)

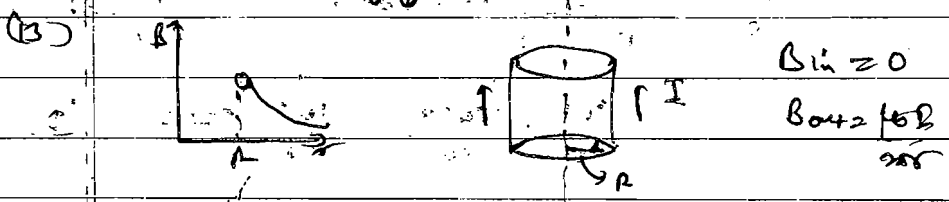
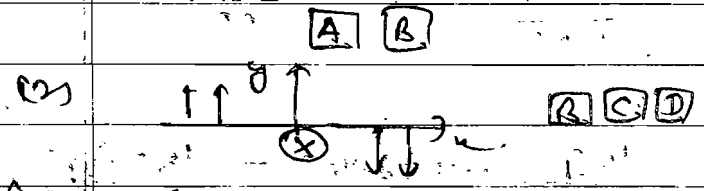
$w_{\text{eff}} = \Delta V B \Rightarrow \frac{1}{2} m (15)^2 = q E_{\text{eff}} a$
 $\frac{159m}{2} = q E_{\text{eff}} a$
 $\therefore v = (159m)$ [A]

(10) $F = \int_{-2a}^{2a} \frac{\mu_0 I}{2} \frac{I' du}{2a} = \frac{\mu_0 I I'}{2a} \ln 3 (-w)$



for $r > R$: $B_{2\pi r} = \frac{\mu_0 I}{r^2} = \frac{\mu_0 I R^2}{r^2}$

$B = \frac{\mu_0 I R^2}{2\pi r^2} = \left(\frac{\mu_0 I}{2\pi R^2} \right) \frac{R^2}{r^2}$



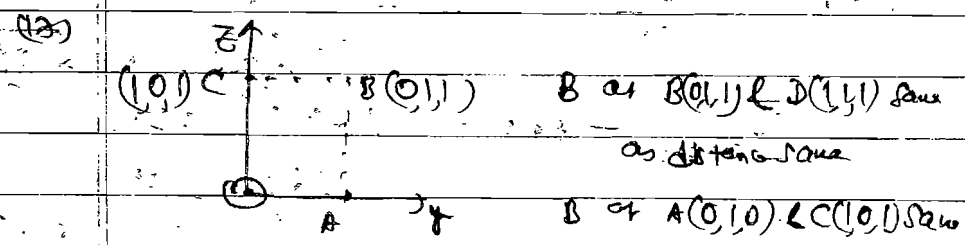
(14) [A] [D] It's Biot-Savart law.

(15) $R = \left(\frac{\mu_0 \gamma}{2\pi} \right) \frac{R_N}{R_M} \quad R_M > R_N$

$R \propto \frac{1}{R} \quad R_{M/2} = 2R \quad [A] [B]$

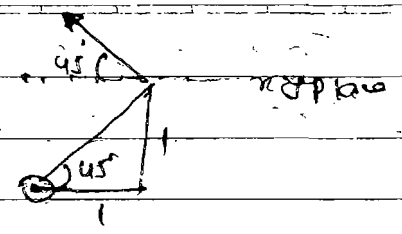
(16) As \vec{r} is parallel to \vec{r}' , so $\vec{r} \times \vec{r}' = 0$ hence $B = 0$

[A] [D]



(18) $B = \frac{\mu_0 I}{2\pi a} = \left(\frac{\mu_0 I}{2\sqrt{2}\pi} \right)$

A D



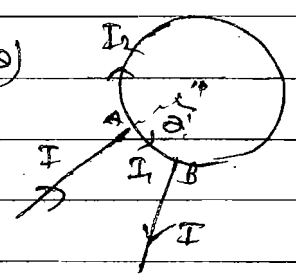
(19) $B_C = \frac{\mu_0 I_1 a}{4\pi R} - \frac{\mu_0 I_2 (a - 0)}{4\pi R}$

$\sqrt{AB} = 0$

$I_1 R_{AB} = I_2 R_{AB}$

$R \propto R \Rightarrow I_1 a = I_2 (a - 0)$

$\Rightarrow B_C = 0$



(20) $B_1 = \left(\frac{\mu_0 I}{4\pi b} + \frac{\mu_0 I}{4\pi a} \right) = \left(\frac{\mu_0 I}{4b} + \frac{\mu_0 I}{4a} \right)$

$B_2 = \left(\frac{\mu_0 I}{4a} - \frac{\mu_0 I}{4b} \right)$, $B_3 = \frac{\mu_0 I}{4a} - \frac{\mu_0 I}{8b} - \frac{\mu_0 I}{8c}$

$B_4 = \left(\frac{\mu_0 I}{4a} + \frac{\mu_0 I}{8b} + \frac{\mu_0 I}{8c} \right)$ ($a > b > c$)

$\therefore (B)_a \text{ is max} \Rightarrow B_4 > B_1 > B_2 > B_3$

A B C

Exercise 3

Comprehension-1

(1) $NTAB = K\theta$

$200 \times 100 \times 10^6 \times \frac{2.1 \times 10^2}{100} \times 0.23 = K \times 28$

$K = 5.2 \times 10^8 \text{ Nm/degree}$ [B]

(2) $K_1 \theta_1 = K_2 \theta_2 \Rightarrow K \times 28 = K \theta_2$
 $\theta_2 = 28^\circ$ [B]

(3) $NDAB = K\theta$

$3NDAB = 3K\theta_0 \Rightarrow \theta_0 = 28^\circ$ [B]

Comprehension-2

(4) $F_{KB} = 200 \times 100 \times 10^6 \text{ N} = 200 \text{ MN}$ [B]

(5) $q_B = 2 \pi r f$

$f = \frac{2 \pi r f_{\text{rot}}}{2\pi} = \frac{2\pi \times 2 \times 10^8 \times 10^{28} \times 20 \times 10^6}{1.6 \times 10^{19}}$ [B]

$= 3.14 \text{ T}$ [B]

(6) $KE = P^2 = \left(\frac{q_B B}{2m}\right)^2 = \frac{(0.265 \times 1.6 \times 10^{19} \times 3.14)^2}{200 \times 1.6 \times 10^{28}}$
 $= 2.7 \times 10^{22} \text{ J}$ [B]

Comprehension-3

(7) $i = nqAv_d$ v_d drift velocity [B]

$v_d = \left(\frac{i}{nqA}\right) = \frac{120}{5.85 \times 10^{28} \times 6.6 \times 10^{-13} \times 11.8 \times 10^{-23} \times 10^6}$ [B]

$= \frac{120}{5.85 \times 10^{19} \times 11.8 \times 10^{-23} \times 10^6} = \frac{120}{5.85 \times 10^2 \times 11.8 \times 10^3}$

$= 4.2 \text{ mm/sec}$ [B]

(8) $E = \Delta V / \Delta d$ $\therefore E = \frac{55 \times 10^5}{11.8 \times 10^3} = 45 \text{ eV}$
 $\Delta V = \frac{IB}{qnA} = \frac{120 \times 0.95}{1.6 \times 10^{19} \times 5.85 \times 10^{28} \times 0.23 \times 10^6}$ [A]

(9) $= 5.14 \text{ eV}$

Match Match Type

(10)

$$I = \frac{q}{2\pi m} \frac{qB}{v} \quad T = \frac{2\pi R}{v} \quad qvB = \frac{mv^2}{R}$$

$$T = \frac{2\pi m}{qB} \quad \therefore R = \frac{mv}{qB}$$

(A) → (r)

$$M = IA \quad \boxed{I = \frac{2\pi m}{qB}}$$

$$M = \left(\frac{q}{2\pi m}\right) \cdot \frac{qB}{v} \cdot \frac{2\pi m}{qB} \cdot v^2$$

(B) → (q)

$$B = \frac{\mu_0 I n}{2\pi R} = \frac{\mu_0 I n}{2\pi \frac{mv}{qB}} = \left(\frac{\mu_0 I q B}{2mv}\right) \quad B \propto \sqrt{I}$$

(D) → (p)

(11)

$$\tau = NIAB \quad (A) \rightarrow (r)$$

$$\tau = I \theta \quad \theta = \frac{NIAB}{C} \quad (B) \rightarrow (s)$$

$$\text{Current sensitivity} = \frac{\theta}{I} = \frac{NIAB}{C} = \frac{NAB \cdot (C)(p)}{C}$$

$$\text{Voltage sensitivity} = \frac{\theta}{IR} = \frac{NIAB}{CIR} = \frac{NAB}{CIR} \quad (D) \rightarrow (q)$$

(12) (D)

(13) (C)

Exercise 4

Subjective 70

① (a) $B = \left(\frac{\mu_0 I}{4\pi a} \right) \left(\frac{2a-\phi}{a} \right) + \frac{\mu_0 I \phi}{4\pi b}$

$$B = \frac{\mu_0 I}{4\pi} \left(\frac{2a-\phi}{a} + \frac{\phi}{b} \right)$$

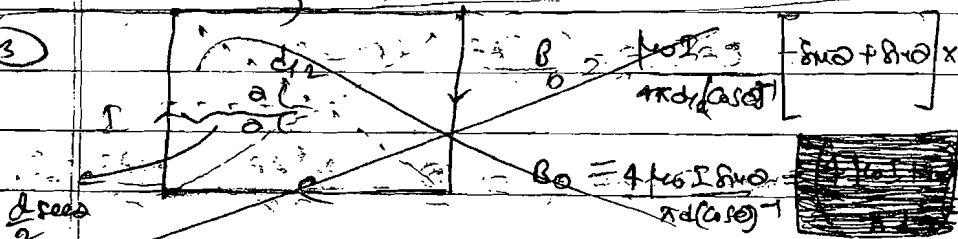
(b) $B = \left(\frac{\mu_0 I}{\pi a} \right) \left(\frac{3\pi}{4} \right) + \frac{\mu_0 I (\sin 45^\circ + \sin 0^\circ) \times 2}{4\pi b}$

$$B = \frac{\mu_0 I}{4\pi} \left(\frac{3\pi}{a} + \frac{\sqrt{2}}{b} \right)$$

② $B = \frac{\mu_0 I (2\pi - 2\phi)}{4\pi R} + \frac{\mu_0 I (2 \sin \phi)}{4\pi R \cos \phi}$

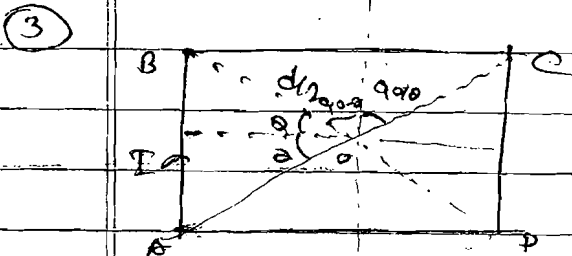
$$B = \frac{\mu_0 I}{2\pi R} \left[(\pi - \phi) + \frac{1}{\cos \phi} \right] = 28 \mu T$$

③ $B_0 = \frac{\mu_0 I a}{4\pi d \cos \theta} \left[\sin \theta + \sin \theta \right] \times 4$



$$B_0 = 4 \frac{\mu_0 I \sin \theta}{\pi d (\cos \theta)^2}$$

$$= 4 \frac{\mu_0 I \sin \theta \cos \theta}{\pi d}$$



$$B = 2 \left[\frac{\mu_0 I (\sin \theta + \sin \theta)}{4\pi d \cos \theta} \right] + 2 \left[\frac{\mu_0 I (\cos \theta + \cos \theta)}{4\pi d \sin \theta} \right]$$

$$= 2 \frac{\mu_0 I [\sin \theta + \cos \theta]}{\pi d} = 4 \frac{\mu_0 I}{\pi d \sqrt{2}} = 0.1 \text{ mT}$$

(4) (a) $B = -\left(\frac{\mu_0 I}{4\pi d}\right)^2 k - \frac{\mu_0 I}{4R}$

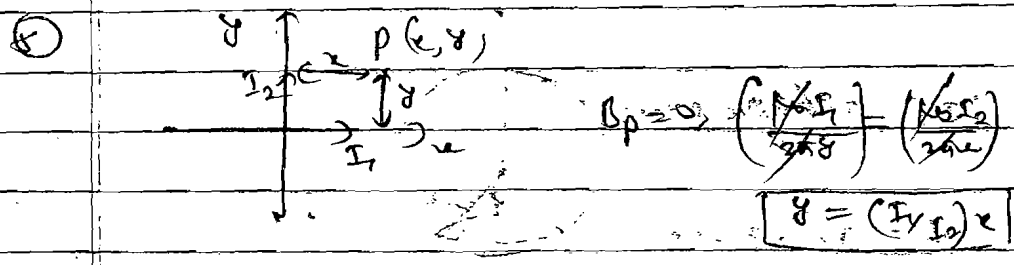
(b) $B = \frac{\mu_0 I}{4\pi R} \sqrt{4 + \pi^2}$

(b) $B_1 = \frac{\mu_0 I}{4\pi R} (-k)$, $B_2 = \frac{\mu_0 I}{4R} (\hat{j})$, $B_3 = \frac{\mu_0 I}{4\pi R} (-\hat{j})$

$B_{net} = \frac{\mu_0 I}{4\pi R} \sqrt{1 + (\pi+1)^2} = \frac{\mu_0 I}{4\pi R} \sqrt{\pi^2 + 2\pi + 2}$

(c) $B_{circular\ loop} = 0$, $B_{straight\ wire} = \frac{\mu_0 I}{4\pi R} (-\hat{k}) + \frac{\mu_0 I}{4\pi R} (-\hat{j})$

$B_{net} = \frac{\mu_0 I}{4\pi R} \sqrt{2}$



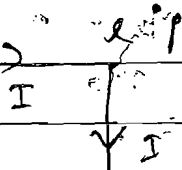
(6) $B_0 = 8\sqrt{2}$

$B_{net} = \sqrt{2^2 + 20^2} + 28^2 \cos 70 + 2 \cdot 20^2 \cos 50 + 2 \cdot 28^2 \cos 15$

$B_{net} = (4R^2 + 20^2 + -20^2)^{1/2} = 28 = 2 \left(\frac{\mu_0 I}{4\pi R}\right)$

(7) $B_{net} = \frac{\mu_0 I}{2a} \left(\frac{1}{\cos \theta} - 1 \right) = \frac{\mu_0 I}{2a} \left(\frac{1}{\cos \theta} - 1 \right)$

7) $B = \frac{\mu_0 I \sqrt{2}}{4\pi R}$

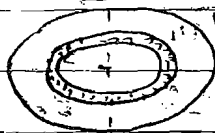


10

8

9

$B = \int \frac{\mu_0 dI}{2r}$



$= \frac{\mu_0}{2} \int_0^R \left(\frac{\sigma 2\pi r dr}{2\pi r} \right) = \frac{\mu_0 \sigma R}{2}$

6) $P = \int_0^R dI \pi r^2 = \int_0^R \sigma 2\pi r dr$

11

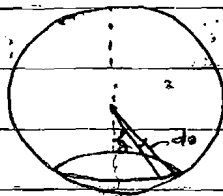
$= \frac{\sigma \omega R^2 \pi}{4} = \pi \sigma \omega R^2$

9

$B = \frac{\mu_0 \sigma \omega R^2}{2(2\pi R)^2}$

$dI = \sigma \omega r^2 dr$

$dI = \sigma R^2 \omega dr$



$B = \left(\int_0^{\pi/2} \frac{\mu_0 \sigma R^2 \omega dr}{2(2\pi R)^2} \right) \times 2$
 (for upper R)

$= \frac{\mu_0 \sigma \omega R}{2} \int_0^{\pi/2} dr = \frac{\mu_0 \sigma \omega R}{2}$
 (lower half)

$I = \int_0^{\pi/2} r dr = \int_0^{\pi/2} (1 - \cos 2\theta) d\theta = 1 - \frac{1}{2} = \frac{1}{2}$
 (r = cos theta)

⑩ ⑨ $B = \frac{2\mu_0 \sigma \omega R}{3}$ (see soln q 9)

$$= \frac{2\mu_0 \sigma \omega R}{3} = \left(\frac{2}{3}\right) \left(\frac{\mu_0}{4\pi}\right) \left(\frac{Q\omega}{a}\right)$$

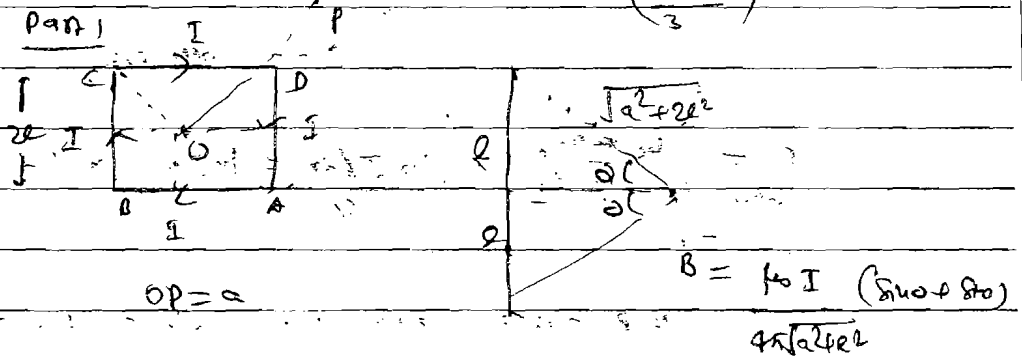
⑪ $P_{\text{rad}} = 2 \int_0^{\pi/2} dA (\pi R \sin\theta)^2 = 2 \int_0^{\pi/2} \sigma \omega a^2 \sin^3\theta d\theta \pi^2 a^2 \sin^2\theta$
 $(R=a) = 2\sigma\omega\pi^2 a^5 \int_0^{\pi/2} \sin^5\theta d\theta$

$$= 4\sigma\omega\pi^2 a^5 \left[\frac{\cos\theta}{1} - \frac{\cos^3\theta}{3} \right]_0^{\pi/2}$$

$$= \left(\frac{2}{3}\right) \sigma \omega a^2$$

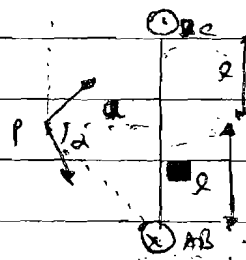
⑪

Part 1



$$B = \frac{\mu_0 I}{4\pi a^2 r} \cdot \frac{2a}{\sqrt{a^2 + 2a^2}} = \frac{\mu_0 I}{2\pi a^2 r} \cdot \frac{2a}{\sqrt{3}a} = \frac{\mu_0 I}{\pi a^2 r} \cdot \frac{2}{\sqrt{3}}$$

Part 2



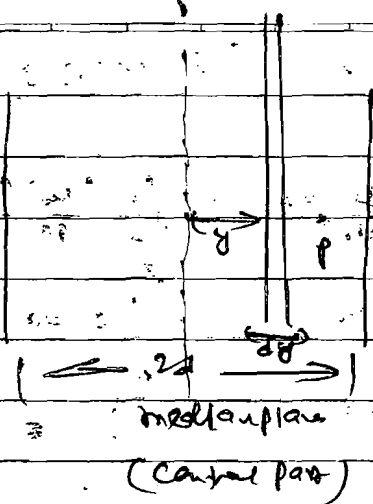
$$B_{\text{net}} = \frac{\mu_0 I}{4\pi r^2} = \frac{\mu_0 I}{4\pi (a^2 + 2a^2)} = \frac{\mu_0 I}{12\pi a^2}$$

$$B_{\text{net}} = \frac{2\mu_0 I}{\pi(a^2 + 2a^2)\sqrt{a^2 + 2a^2}}$$

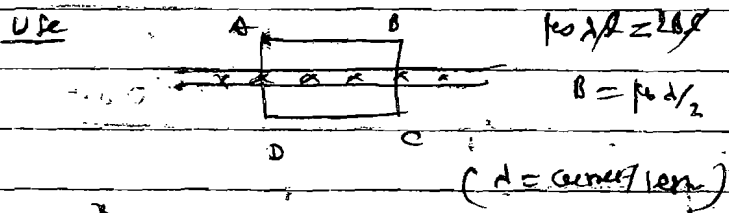
Put $I = 30$, $a = 3$ cm, $\mu_0 = 2.65 \times 10^{-4}$

$$B = 2.2 \times 10^{-4} \text{ T}$$

(12)



(17)



~~$B = \frac{\mu_0 I}{2}$~~

$$B = \int_{-a}^{+a} \frac{\mu_0 \left(\frac{I}{2a}\right)}{2} = \int_{-a}^{+a} \frac{\mu_0 I}{4a} dx = \frac{\mu_0 I}{4a} (x \text{ Cd})$$

(14)

We have to integrate from $-x$ to x as $(d-x)$ on left & right with conductor

(13)

Why amper's law?

(b) $B = 0$ $r < a$
 $B = \frac{\mu_0 I r}{2\pi r^2}$ $a < r < b$

$$I_{enc} = \frac{I(r^2 - a^2)}{\pi(b^2 - a^2)} = \frac{I(r^2 - a^2)}{b^2 - a^2}$$

$$B = \frac{\mu_0 I (r^2 - a^2)}{2\pi r (b^2 - a^2)}$$

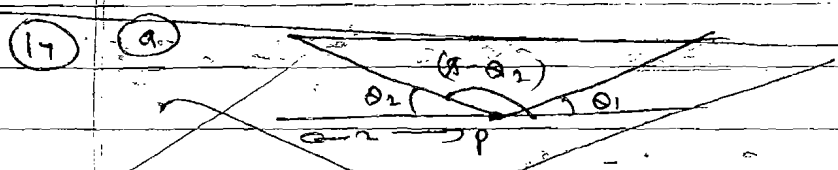
$$B = \frac{\mu_0 I}{2\pi r} \quad r > b$$

(c) $qvB = mv^2 \Rightarrow R = \frac{mv}{qB}$

$T = \frac{2\pi R}{v} = \left(\frac{2\pi m}{qB}\right) \cdot \omega = \frac{v}{R} = \frac{qB}{m}$

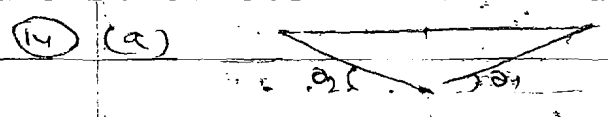
$\alpha = \omega r = \left(\frac{qB}{m}\right) \left(\frac{L}{v}\right) = \left(\frac{qBL}{mv}\right)$

$= \left(\frac{qL}{mv}\right) (\mu_0 I) = \left(\frac{\mu_0 I qL}{2\pi r v}\right)$

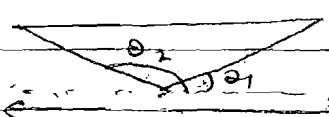


~~$B = \frac{\mu_0 n I}{2} (\cos \theta_1 - \cos \theta_2)$; $B = \frac{\mu_0 n I}{2} (-\cos \theta_2 + \cos \theta_1)$~~

~~for semi infinite $\theta_1 = 0$, $B = \frac{\mu_0 n I}{2} \left(1 - \frac{2}{\sqrt{1-x^2}}\right)$~~



$B = \frac{\mu_0 n I}{2} (\cos \theta_1 + \cos \theta_2)$



$B = \frac{\mu_0 n I}{2} (\cos \theta_1 - \cos \theta_2)$

$\theta_1 = 0$ $\cos \theta_1 = \cos \theta_2 = \cos \theta_2$ $\cos(\theta_2 - \theta_1) = -x/\sqrt{1-x^2}$ $\cos \theta_2 = x/\sqrt{1-x^2}$
(semi infinite) $B = \frac{\mu_0 n I}{2} \left(1 - \frac{x}{\sqrt{1-x^2}}\right)$

(b) $\frac{B_0 - B}{B_0} = \frac{1 - B}{1} = 1 - \eta$ $B_0 = \frac{\mu_0 n I}{2}$ $B = \frac{\mu_0 n I}{2} \left(1 - \frac{x}{\sqrt{1-x^2}}\right)$
 $1 - \frac{\mu_0 n I}{2} \left(1 - \frac{x}{\sqrt{1-x^2}}\right) = 1 - \eta$

(19)

$$n = 1 - 2y$$

$$\frac{n^2}{2} = (n^2 - 2ny)(1 - 2y)^2$$

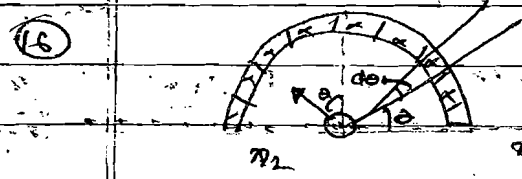
$$4ny = 4n^2 \Rightarrow \dots (1 - 2y)^2$$

$$4n(1 - y)^2 = 2^2(1 - 2y)^2$$

$$x = \frac{2(1 - 2y)}{2n(1 - y)} = \frac{1 - 2y}{n(1 - y)}$$

(15) $F = \int \frac{\mu_0 I_1 I_2 dx}{2\pi r^2} = \frac{\mu_0 I_1 I_2}{2\pi} \ln\left(\frac{a+r}{a}\right)$

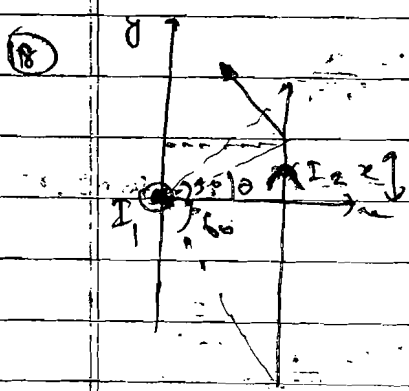
$$F = \frac{\mu_0 I_1 I_2}{2\pi} \ln(1 + \frac{r}{a})$$



$$B_{net} = \int dB \sin\theta = \int \frac{\mu_0 I dl}{4\pi R^2} \sin\theta = \frac{\mu_0 I}{4\pi R^2} \int \sin\theta dl$$

$$F = \frac{\mu_0 I^2}{2\pi R}$$

(17) $F = \int \frac{\mu_0 I_1 I_2 dx}{2\pi r^2} = \frac{\mu_0 I_1 I_2}{2\pi a} \ln\left(\frac{a+b}{a}\right)$



$$F = \int (dB \sin\theta) I_2 dx$$

(20)

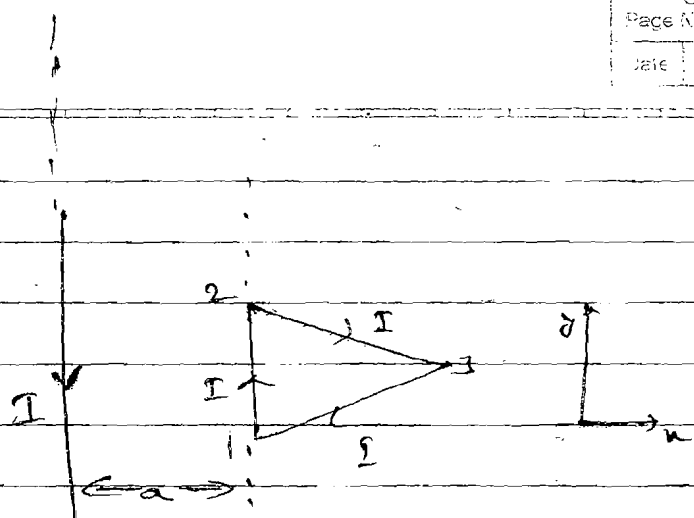
$$F = \int \frac{\mu_0 I_1 I_2}{2\pi a \ln^2 \frac{a+b}{a}} dx$$

$$F = \int \frac{\mu_0 I_1 I_2}{2\pi a} dx$$

(21)

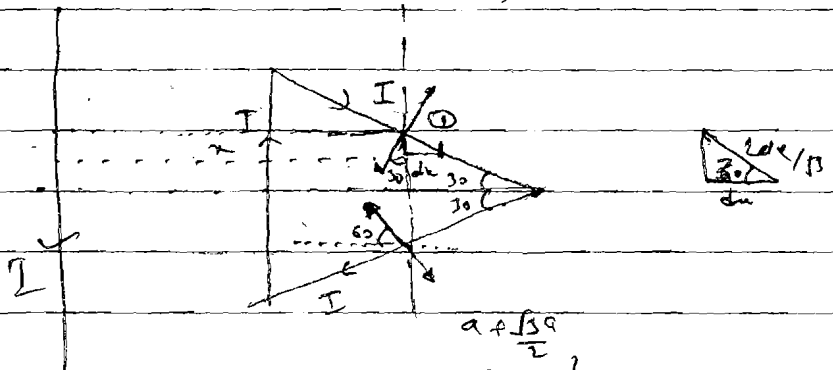
$$-B a = \mu_0 I_1 I_2 (\ln y - \ln 1) / R$$

(19)



$$\vec{F} = \vec{F}_{12} + \vec{F}_{21} + \vec{F}_{31}$$

$$\vec{F}_{12} = \frac{\mu_0 I^2}{2\pi a} \hat{i}$$



$$F = \int \frac{\mu_0 I^2 (du) \sqrt{3}}{2\pi a} \times \frac{a + a\sqrt{3}}{2} = \frac{\mu_0 I^2 \sqrt{3}}{2\pi} \ln\left(\frac{2\sqrt{3}}{2}\right) (\hat{i} + \hat{j})$$

$$\vec{B} = \frac{\mu_0 I^2}{\pi} \hat{i} + \frac{\mu_0 I^2}{\pi} \ln\left(\frac{2\sqrt{3}}{2}\right) (\hat{i} + \hat{j})$$

(20)

form \vec{M} loop by adding for additional wires:

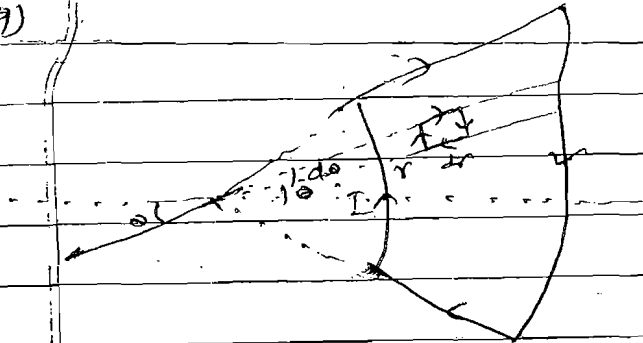
$$\vec{M} = Ie^2 \hat{k} + Ie^2 - \hat{k} + Ie^2 \hat{i}$$

$$\vec{M} = Ie^2 \hat{i}$$

(21)

$$B = \int \frac{\mu_0 d\vec{M}}{2\pi r} = \frac{\mu_0}{2} \left(\frac{0 \times 0 \times 0}{r} \right) = \dots$$

(29)



(31)

$$dA = (r da) dr$$

$$dM = r I da dr ; \mu = \frac{\mu_0 I_0}{2\pi r}$$

$$dz = dm \sin 90^\circ$$

$$dz = \int r I da dr \frac{\mu_0 I_0}{2\pi r} = \frac{\mu_0 I I_0}{2\pi} da dr$$

towards center

$$Z_{net} = \int dz \cos 0$$

$$Z_{net} = \frac{\mu_0 I I_0}{2\pi} \int_{-a}^a da \int_0^b dr = \frac{\mu_0 I I_0 (\sin a) (b-a)}{\pi}$$

$$Z_{net} = \frac{\mu_0 I I_0 \sin a (b-a)}{\pi} \quad \begin{matrix} \text{towards} \\ \text{left} \end{matrix}$$

(32)

$$(30) (a) \quad \vec{M} = I_2 \vec{A} \quad \vec{A} = (\vec{B} \times \vec{A}) \times (\vec{A} \times \vec{B})$$

$$\vec{A} = (2d\hat{i} - 2a\hat{j}) \times 2b\hat{k}$$

(33)

$$= 4b (d\hat{i} - a\hat{j}) \times \hat{k}$$

$$\vec{A} = -4b (d\hat{i} + a\hat{j})$$

$$\vec{M} = -I_2 4b (d\hat{j} + a\hat{i})$$

(b)

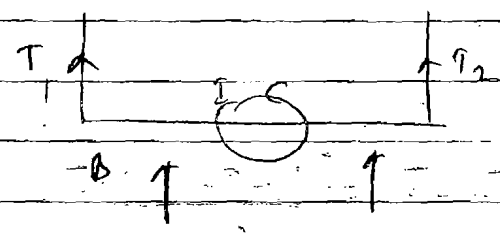
$$\vec{B} = \frac{\mu_0 I_1}{2\pi r} \hat{j}$$

$$U_2 = \vec{M} \cdot \vec{B} = I_2 4b \frac{\mu_0 I_1}{2\pi r} d$$

$$P = -\frac{dU}{dt} = \left(\frac{2\mu_0 b d I_1 I_2}{\pi r_0^2} \right) \hat{i}$$

$$U_{tc} \left[\vec{F} = - \left(\frac{\partial U}{\partial x} \hat{i} + \frac{\partial U}{\partial y} \hat{j} + \frac{\partial U}{\partial z} \hat{k} \right) \right]$$

(31)



moment about 1

$$Z_{net} = Z_{T2} + Z_B$$

$$T_0 L = I \pi R^2 B$$

$$T_2 = \left(T_0 - \frac{I \pi R^2 B}{L} \right)$$

moment about 2

$$Z_{\pi} = Z_B + Z_{T2}$$

$$\pi L = T_0 L + I \pi R^2 B$$

$$\pi = T_0 + \frac{I \pi R^2 B}{L}$$

(32)

$$Z_B = Z_{net} \Rightarrow \frac{M \sin \theta}{r} = M \sin \theta$$

$$\Rightarrow \frac{I \pi R^2 B}{L} = I \pi R^2 B \Rightarrow \theta = \frac{2 \sin \theta}{\sqrt{3}}$$

(33)

By conservation of angular momentum; about common diameter

$$\frac{m r^2 \omega_1}{2} = \frac{M R^2 \omega_2}{2} \Rightarrow \omega_2 = \frac{m (r^2)}{M (R^2)} \omega_1 \quad \text{--- (1)}$$

By C.O.E

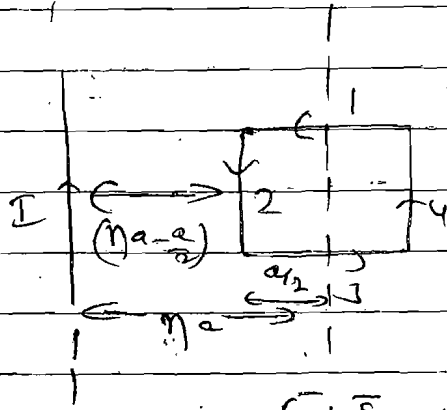
$$\frac{1}{2} \frac{m r^2 \omega_1^2}{2} + \frac{1}{2} \frac{M R^2 \omega_2^2}{2} = -\vec{p} \cdot \vec{B} = \mu_0 I_1 I_2 A R^2 \quad \text{--- (2)}$$

Solving (1) & (2)

$$\frac{1}{2} \left(\frac{m r^2}{M R^2} \right) \omega_1^2 = \mu_0 I_1 I_2 A R^2$$

(37) (a)

(35)



$$F_1 + F_2 = 0$$

$$F_{net} = F_1 + F_2 = \left[\frac{\mu_0 I_0}{2\pi(n-2)a} \right] (Ia)$$

$$- \frac{\mu_0 I_0 (Ia)}{2\pi(n+2)a} \uparrow$$

$$= \frac{\mu_0 I_0 I a^2}{\pi a^2} \left(\frac{1}{2n-1} - \frac{1}{2n+1} \right)$$

(36)

$$= \frac{\mu_0 I_0 I 2}{\pi 4n^2} = \left[\frac{2 \mu_0 I_0 I}{\pi (4n^2-1)} \right] \uparrow$$

(b)

$$W = \Delta PE$$

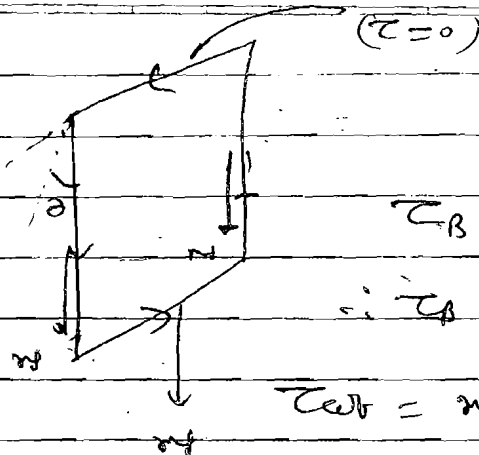
$$= 2 \mu_0 I_0 I a^2$$

(38)

$$= 2 \int_{na-2a}^{na+2a} \frac{\mu_0 I (I_0 a de)}{2\pi r}$$

$$W = \frac{\mu_0 I_0 I a}{\pi} \ln \left(\frac{2n+1}{2n-1} \right)$$

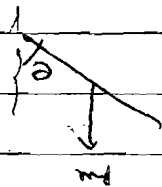
(15)



$$\tau_B = I R^2 B \sin(90-\theta)$$

$$\therefore \tau_B = I R^2 B \cos\theta$$

$$\tau_{\text{net}} = \frac{mg \cdot 2a}{2} + \frac{mg \cdot 2b}{2} \sin\theta + \frac{mg \cdot 2b}{2} \cos\theta$$



$$\tau_{\text{net}} = 2mg \cos\theta = 2(2aI)g \cos\theta = 2(8aI^2 g \sin\theta)$$

$$\text{for eq: } \tau_{\text{net}} = \tau_B$$

$$I^2 \cos\theta = 2(8aI^2 g \sin\theta)$$

$$\boxed{B = \frac{2(8aI^2 g \sin\theta)}{I}}$$

(16)

(a) $F = 0$

(b) $U = -\vec{p}_m \cdot \vec{B} = -p_m \frac{\mu_0 I}{2\pi r}$

$$F = -\frac{dU}{dr} = \frac{p_m \mu_0 I}{2\pi r^2} = \frac{\mu_0 (2I p_m)}{4\pi r^2}$$

(c) $\mu_0(B)$

(17)

$$B = \frac{\mu_0 2I p_m}{4\pi r^2}$$

$$U = -\vec{p}_m \cdot \vec{B} = \left(\frac{\mu_0 p_m I p_m}{2\pi r^2} \right)$$

$$F = -\frac{dU}{dr} = \frac{2 \mu_0 p_m I p_m}{2\pi r^3} = \left(\frac{2 \mu_0 p_m I p_m}{\pi r^3} \right)$$

(38)

$$\tau = I L B \sin \theta$$

$$\approx I L B \theta = I \alpha$$

(41)

$$I L B \theta = \left[\frac{m l^2 \times 2}{12} + \frac{m l^2 \times r^2}{16} \right] \omega$$

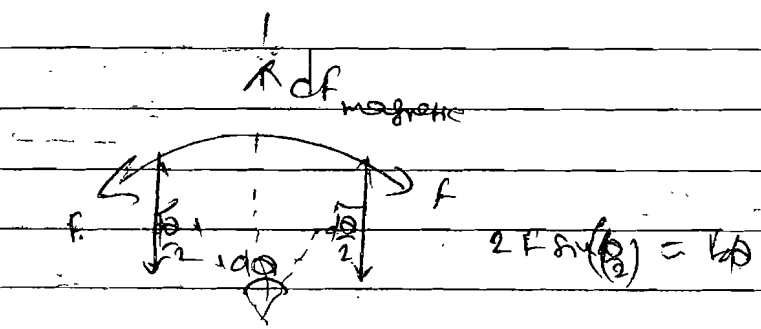
$$I B = \frac{m \omega^2}{6 J \pi a} = \frac{\omega}{J \pi a} \Rightarrow \sqrt{6 I B} = \frac{2\pi}{T}$$

$$T = \frac{2\pi}{\sqrt{6 I B}} m = \frac{2\pi}{\sqrt{6 \times 2 \times 0.1}}$$

$$= \frac{2\pi}{\sqrt{120}} = \frac{2\pi}{11} = \frac{2 \times 3.142}{11} = 0.57 \text{ sec}$$

(42)

(39)



$$W = d f_{\text{magnetic}}$$

(43)

$$I R d \sin \theta = W$$

$$F = I B R$$

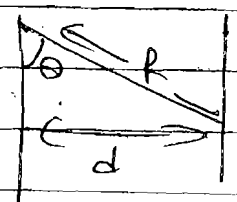
$$l = 2\pi R$$

$$d = 2R$$

(44)

$$\frac{F}{k} = \frac{2\pi R d}{k} \Rightarrow d = \frac{F}{2\pi k} = \frac{(I B R)}{2\pi k}$$

(40)



$$\sin \theta = \frac{d}{R}$$

$$\omega = \sin^{-1} \left(\frac{d}{R} \right) = \alpha$$

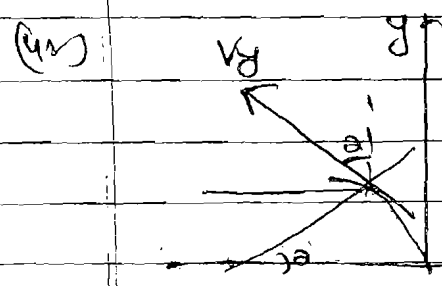
(41) $\frac{1}{2}mv^2 = q \cdot V_0 \Rightarrow P = \sqrt{2mqV_0}$

$R = mv = \frac{p}{qB} \therefore 2R = \left(\frac{2p}{qB}\right)$

$l + d = \frac{2}{qB} \sqrt{2mqV_0}$

$l = \frac{2}{qB} \sqrt{2mqV_0} = \left(\frac{l+d}{2}\right)^2 = \frac{m}{m_1}$

$\therefore \frac{m_1}{m} = \left(\frac{l+d}{2}\right)^2$



$V = V_x \hat{i} + V_y \cos \omega t \hat{j} + V_y \sin \omega t \hat{k}$

$\omega = \frac{qB}{m}$

$T = \frac{2\pi}{\omega} = \frac{2\pi m}{qB} \therefore \omega = \frac{qB}{m}$

(43) By COE $\frac{1}{2}mv^2 = qEz$

$\therefore v = \sqrt{\frac{2qEz}{m}}$

(44) $P = \vec{r} \times \vec{F} = q\vec{r} + i(\vec{v} \times \vec{r})$

$\vec{F} = qB\hat{j} + q(v_x\hat{i} + v_y\hat{j}) \times B(\hat{k})$

$F = -qB\hat{i} + qBv_x\hat{i} - qv_yB\hat{j}$

$f_x = eV_yB, f_y = (eE - eBv_x)$

$m \frac{dv_x}{dt} = eV_yB, m \frac{dv_y}{dt} = eE - eBv_x$ (2)

So $\frac{dy}{dt} = 0$ we get (45)

$$m \frac{d^2 y}{dt^2} = -eB \frac{dy}{dt}$$

$$m \frac{d^2 y}{dt^2} = -\frac{eB \cdot eB}{m} y$$

$$\frac{d^2 y}{dt^2} = -\left(\frac{eB}{m}\right)^2 y$$

$$y = A \sin\left(\frac{eBt}{m}\right) \quad (46)$$

$$\text{At } t=0 \quad y=0 \Rightarrow \phi=0$$

$$y = A \sin\left(\frac{eBt}{m}\right)$$

$$\text{When } \frac{dy}{dt} = 0 \quad y=0 \Rightarrow \frac{eBt}{m} = 0, \pi, 2\pi, \dots$$

$$\frac{dy}{dt} = \frac{A eB}{m} \cos\left(\frac{eBt}{m}\right)$$

(47)

$$\frac{eB}{m} = \frac{A eB}{m} \quad \text{At } t=0$$

$$A = \frac{E_0}{B}$$

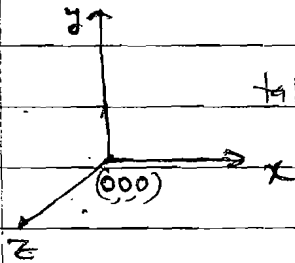
$$y = \frac{E_0}{B} \sin\left(\frac{eBt}{m}\right) \quad \left(\frac{eB}{m} = \omega\right)$$

$$y = \frac{E_0}{B\omega} (1 - \cos\omega t)$$

$$\text{So } y = \frac{E_0}{B\omega} (1 - \cos\omega t)$$

$$\text{So, } y_{\text{max}} = \frac{E_0 (1 - \cos\pi)}{B\omega} = \frac{2E_0 m}{B\omega}$$

(45)

take $\alpha = 65^\circ$, Pitch = $0.05 \text{ m} = 5 \text{ cm}$

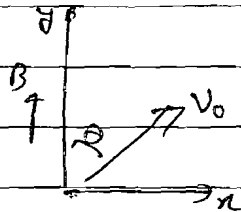
$$\left(\frac{2\pi m}{qB}\right)(V_0 \cos \alpha) = d$$

$$\frac{1}{2} m v_0^2 = 2 \text{ eV} \therefore v_0 = \sqrt{\frac{2 \times 2 \text{ eV}}{m}}$$

$$\text{So, } \left(\frac{2\pi m}{qB}\right) \sqrt{\frac{2 \times 2 \text{ eV}}{m}} \cos 60 = d \therefore \beta = 6.9 \times 10^7 \text{ T}$$

Substitute the values

(46)



Part 1:

$$V_0 \cos \theta = v \text{ speed}$$

By C.E:

$$\frac{1}{2} m v_0^2 = 2 \text{ eV} \therefore v_0 = \sqrt{\frac{2 \times 2 \text{ eV}}{m}}$$

$$v \cos \theta = \left(\sqrt{\frac{2 \times 2 \text{ eV}}{m}}\right) \cos \theta$$

Part 2:

Distance = Pitch = $(v \cos \theta) T$

$$= \left(\frac{2 \times 2 \text{ eV}}{m}\right) \cos \theta \left(\frac{2\pi m}{qB}\right)$$

(47)

Initially $q v \cos \theta = e E$

$$v = \left(\frac{E}{B \cos \theta}\right)$$

When E off: Pitch = $P = T (v \sin \theta)$

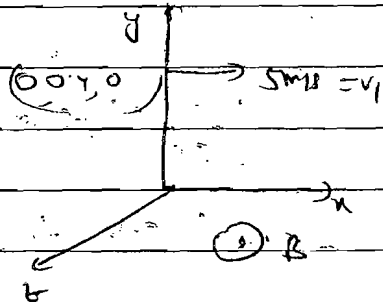
$$= \left(\frac{2\pi m}{qB}\right) \left(\frac{E \sin \theta}{B \cos \theta}\right)$$

$$= \frac{2\pi m E \sin \theta}{q B^2 \cos \theta}$$

$$= \frac{2\pi m E \tan \theta}{q B^2}$$

$$= \left(\frac{2\pi m E \tan \theta}{q B^2}\right)$$

(48)



Radius of circle path by this particle is r_1

$$but \quad r_1 = \frac{(m v_1)}{q_1 B}$$

$$B = \frac{(m v_1)}{q_1 r_1} = 0.5 T$$

For 1st & 2nd particle use CM (Conservation of

linear momentum)

$$(m_1 + m_2) v_c = m_1 v_1 + m_2 v_2$$

$$(40 \times 10^{-3} + 10 \times 10^{-3}) v_c = (40 \times 10^{-3}) 5 \hat{i} + (10 \times 10^{-3}) 40 \hat{j}$$

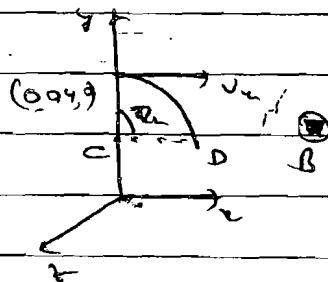
$$\Rightarrow v_c = 4 \text{ m/s}$$

$$v_c = 8 \text{ m/s}$$

due to v_c circular motion

$$R = \frac{(m_1 + m_2) v_c}{(q_1 + q_2) B} = 0.2 \text{ m}$$

$$T = \frac{2\pi (m_1 + m_2)}{(q_1 + q_2) B} = \frac{\pi}{10} \text{ sec}$$



angular displacement due to circular motion

$$\theta = \omega t = \frac{\pi}{2}$$

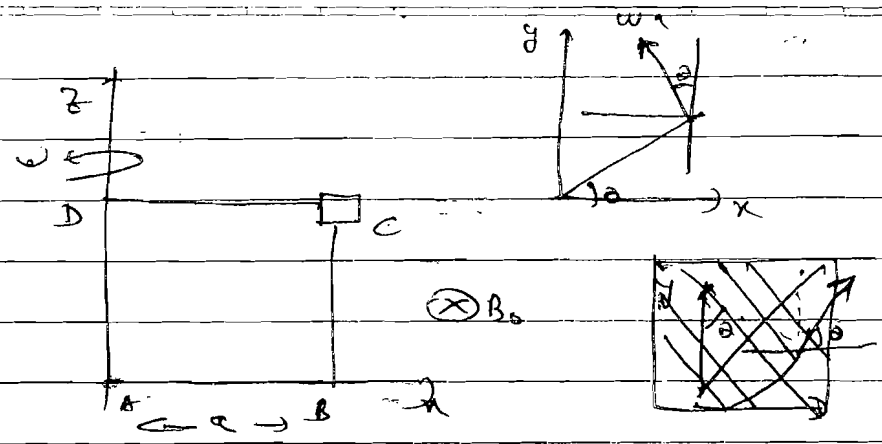
$$x_{\text{center}} = R \sin \theta = 0.2$$

$$y_{\text{center}} = 0.2 + R \cos \theta = 0.2 + 0 = 0.2$$

$$z_{\text{center}} = \frac{v_c}{\omega} = 0.2$$

$$\therefore \text{position} = (0.2, 0.2, 0.2)$$

(49)



v_{speed} of slider wa in xy plane

$$\vec{v} = wa(-\sin\alpha \hat{i} + \cos\alpha \hat{j} + v_z \hat{k})$$

$$\vec{F} = q\vec{v} \times \vec{B} = wa(-\sin\alpha \hat{i} + \cos\alpha \hat{j} + v_z \hat{k}) \times B_0 \hat{k}$$

$$\vec{F}_z = waB_0 \sin\alpha (-\hat{i})$$

$$a_z = \frac{waB_0 \sin\alpha (-\hat{i})}{m} = \frac{dv_z}{dt}$$

$$v_z = \int dv_z = - \int_0^t \frac{waB_0 \sin\alpha}{m} dt$$

$$v_z = - \frac{waB_0}{m} (1 - \cos\omega t)$$

$$v_z = - \frac{aB_0}{m} (1 - \cos\omega t) = \frac{dz}{dt}$$

$$\int dz = - \frac{aB_0}{m} \int (1 - \cos\omega t) dt$$

$$z = - \frac{aB_0}{m} (t - \frac{\sin\omega t}{\omega}) = \frac{a}{\omega}$$

$$B_0 = \left(\frac{m\omega}{a} \right)$$

(50) (A) $\frac{1}{2}mv^2 = qV_0$
 ($V_0 = \int E \cdot dy$)

(1)

$$v = \sqrt{\frac{2qV_0}{m}}$$

$$\frac{dz}{dt} = \frac{qE t^2}{2m} = \frac{qE \left(\frac{a}{v}\right)^2}{2m}$$

(2)

$$= \frac{1}{2} \frac{qE a^2}{m v} = \frac{E a^2}{4V_0}$$

(B) Pitch = $T \left(\frac{qE}{m} \right) t$

$$= \left(\frac{2\pi m}{qB} \right) \left(\frac{qE}{m} \right) \left(\frac{a}{v} \right)$$

(3)

$$= \frac{2\pi E a}{B \sqrt{2qV_0}}$$

$$\text{Pitch} = \frac{\pi E a}{B} \sqrt{\frac{2m}{qV_0}}$$

(4)

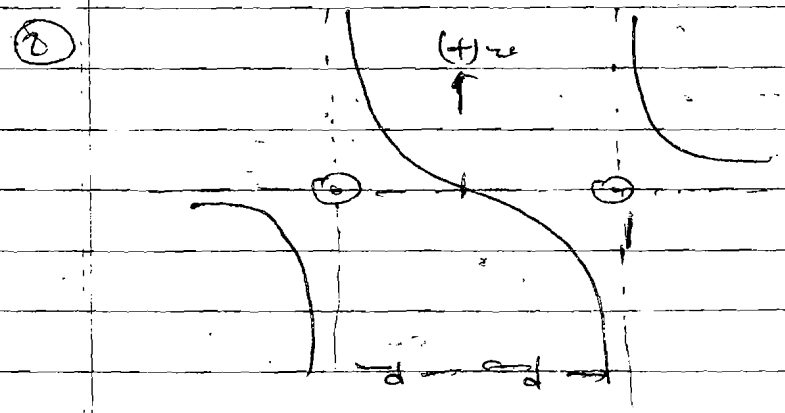
(5)

See Problems

Single choice

①
$$\frac{M}{L} = \frac{2\pi r^2}{T} = \frac{2\pi r^2 \omega}{2\pi r^2 \omega T} = \frac{2}{2m}$$

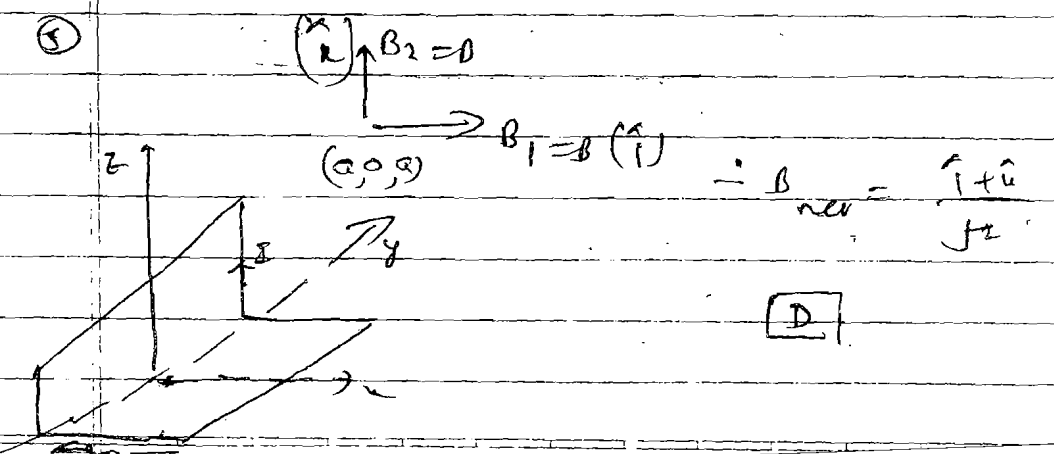
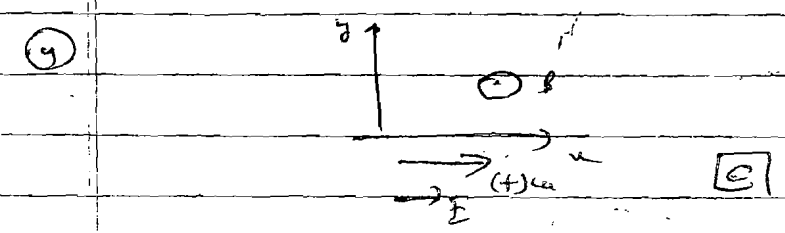
[S]



③
$$n_1 = \frac{\mu_0 I}{4\pi d}$$

$$n_2 = \frac{\mu_0 I}{4\pi d} + \frac{\mu_0 I}{8\pi d} = \frac{\mu_0 I}{4\pi d} \left(\frac{3}{2} \right) = n_1 \cdot \frac{3}{2}$$

$$\frac{n_1}{n_2} = \frac{2}{3}$$
 [C]



(6) $R_A > R_B$

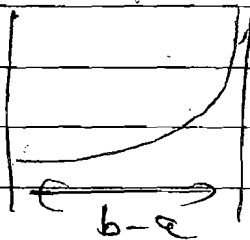
$$\frac{m_A v_A}{a_B} > \frac{m_B v_B}{a_B} \Rightarrow m_A v_A > m_B v_B \quad (11)$$

[B]

(7) $B = \int \frac{\mu_0 I N}{2\pi r} dr$ (12)

$$\therefore B = \frac{\mu_0 N I}{2(b-a)} \ln\left(\frac{b}{a}\right) \quad [C]$$

(8) (13)



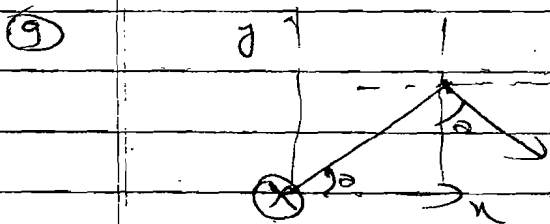
$$\frac{m v}{a b} = \rho (b-a)$$

$$m v = (b-a) a b \quad (14)$$

$$v = \frac{q (b-a) B}{m} \quad [B]$$

(15)

(16)



$$B = \frac{\mu_0 I}{2\pi \sqrt{l^2 + y^2}} (\hat{i} \sin\theta - \hat{j} \cos\theta)$$

$$\therefore B = \frac{\mu_0 I}{2\pi \sqrt{l^2 + y^2}} (y \hat{i} - x \hat{j}) \quad [A]$$

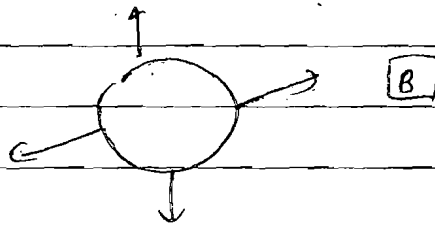
(17)

(10) [D] circuit loop
N to S out
S to N in

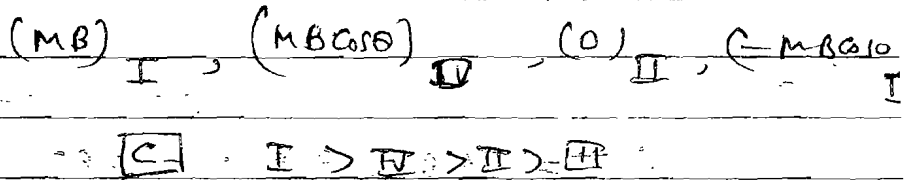
(11) B must have \uparrow net $\vec{a}_B \downarrow$

\rightarrow B

(12)



(13)



(14)

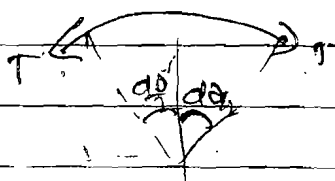
speed $\propto R \omega \cos \theta$

B

(15)

direction will be same as \vec{a} \rightarrow A

(16)



$2r \sin \frac{\alpha}{2} = IR \sin \alpha$

$T d\alpha = IR d\alpha$

$\therefore T = IR \quad L = 2\pi R$

$T = \frac{IRL}{2\pi}$

$R = \frac{L}{2\pi}$

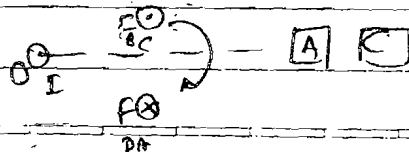
C

MULTIPLE CHOICE

(17)

$F_{AB} = 0 = F_{CD}, \quad F_{BC} = F_{DA}$

\therefore net zero



(18)

$$\frac{2mv}{qB} = R > l$$

(21)

$$v > qBR \quad [a]$$

[c] [d] Time period = $2\pi m$

independent of v

Subjective Problem

(19)

In eq^m $2T_0 = m\omega^2 r \therefore T_0 = \frac{m\omega^2 r}{2}$, $T = mBR\omega^2$

$$\therefore T = (IA)B = \frac{(q\omega r)^2}{2} B = \frac{\omega^2 B q^2 r^2}{2}$$

Let T_1 & T_2 tension in string when magnetic field is switched

on $(T_1 + T_2) \sin \theta = (T_1 - T_2)$ for rotation eq^m above

$$(T_1 - T_2) \frac{r}{2} = \frac{\omega^2 B q^2 r^2}{2} \Rightarrow T_1 - T_2 = \omega^2 B q^2 r \quad (ii)$$

$$\therefore T_1 = \frac{m\omega^2 r}{2} + \frac{\omega^2 B q^2 r^2}{2} \quad T_0 + \frac{\omega^2 B q^2 r^2}{2} = \frac{1}{2} T_0 \therefore \omega = \frac{(\frac{1}{2} T_0)}{m r}$$

(20)

$$\frac{P_p}{P_\alpha} = \frac{q_p v_p q_\alpha r}{q_\alpha m_\alpha v_\alpha} = \frac{1}{2} \left(\frac{v_p}{v_\alpha} \right) \quad \text{--- (1)}$$

$$\text{also, } q_\alpha v = \frac{1}{2} m_\alpha v_\alpha^2 \quad \text{--- (A)}$$

$$q_p v = \frac{1}{2} m_p v_p^2 \quad \text{--- (B)}$$

(22)

(A)/(B)

$$\frac{2 q_\alpha}{q_p} = \frac{m_p}{m_\alpha} \left(\frac{v_\alpha}{v_p} \right)^2$$

$$\frac{1}{2} = \left(\frac{v_\alpha}{v_p} \right)^2 \therefore \frac{v_p}{v_\alpha} = \sqrt{2}$$

$$\text{So } \textcircled{1} \frac{P_p}{P_\alpha} = \frac{1}{2}$$

(21) (a) $N \perp AB = k \perp$
 $k = \frac{N \perp AB}{\perp} = N \perp AB$
 $k = N \perp AB$

(b) $N \perp AB = \frac{\tau \perp}{k \perp}$
 $\tau = \frac{2N \perp AB}{\perp} = \text{Total normal com}$

(c) $\tau = B \perp NA$
 $\int_0^{\omega} \tau d\omega = \tau \omega \Rightarrow B \perp NA \omega = \tau \omega$
 $\omega = B \perp NA$

By C.O.E At max^m deflection total KE is converted into P.E

(Just linear is covered to C.O.E)

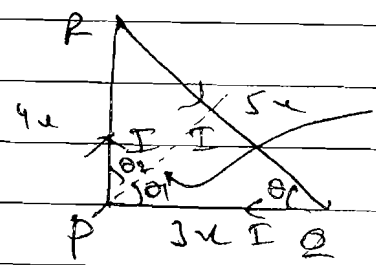
$\frac{1}{2} I \omega^2 = \frac{1}{2} k \omega^2 \Rightarrow \frac{1}{2} I (B \perp NA)^2$

$= \frac{1}{2} \frac{2B \perp NA^2 \omega^2}{\pi \dots}$

$I \frac{B \perp NA^2 \omega^2}{\perp^2} = \frac{2B \perp NA^2 \omega^2}{\pi}$

$\omega = \sqrt{\frac{\pi B \perp NA^2}{2I}} = \omega \sqrt{\frac{B \perp NA}{2I}}$

(22)



$\sin \theta = \frac{d}{5} = \frac{4}{5} \therefore d = \frac{12u}{5}$

$B_p = \frac{k \omega I}{4 \times (\frac{12u}{5})} [0.5 \theta + 8u \omega]$

(23) $P \perp \omega$ as $\vec{M} \parallel -\hat{k}$

$$MB = \frac{mgR}{2} \Rightarrow I \alpha = mgR$$

$$\therefore \alpha = \frac{mg}{2I} = 3\frac{g}{R}$$

$$\vec{F} = -I b \hat{j} \times (3\hat{i} + 4\hat{k}) R$$

$$\vec{R} = I b B_0 (\hat{i} - 4\hat{j}) \quad I = \frac{mg}{6bB_0}$$

(24)

$$B_{\text{center}} = \left(\frac{\mu_0 I_1}{4R_1} + \frac{\mu_0 I_2}{4R_2} \right) = \frac{\pi \times 10^{-7}}{4 \times 4} \begin{bmatrix} 10 & 10 \\ 0.02 & 0.03 \end{bmatrix}$$

$$= 6.54 \times 10^{-5} \text{ T}$$

$$F = 6.54 \times 10^{-5} \times 10 \times 8 \times 10^{-2}$$

$\therefore F = 0$

$$F_{\text{CP}} = \int \frac{\mu_0 I^2 da}{2\pi r} = \frac{\mu_0 I^2}{2\pi} \ln\left(\frac{r_2}{r_1}\right)$$

$$= \frac{\mu_0 I^2}{2\pi} \ln\left(\frac{3}{2}\right) = 8 \times 10^{-7} \text{ N}$$

(25) D

(26) D

(27) B

(28) C